

声学多普勒流速剖面仪（ADCP）及其应用

Introduction of ADCP and its application

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Beijing, China

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Outline



中国科学院声学研究所
Institute of Acoustics, CAS

- 1. Introduction to ADCPs**
- 2. Product Classification**
- 3. Application (QA/QC)**
- 4. About Us (Institute of Acoustics, CAS, China)**

1. Introduction to ADCPs (1/4)

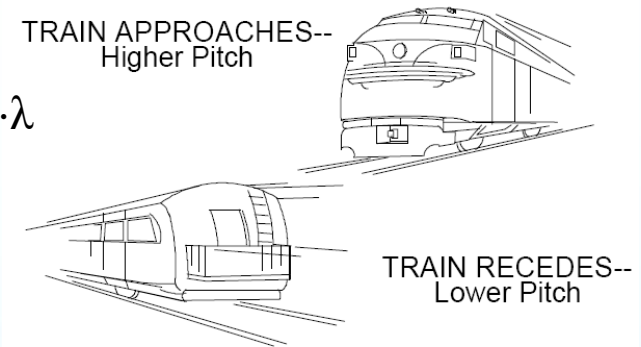


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□ The Doppler Effect

Speed of sound = frequency \times wavelength: $C = f \cdot \lambda$

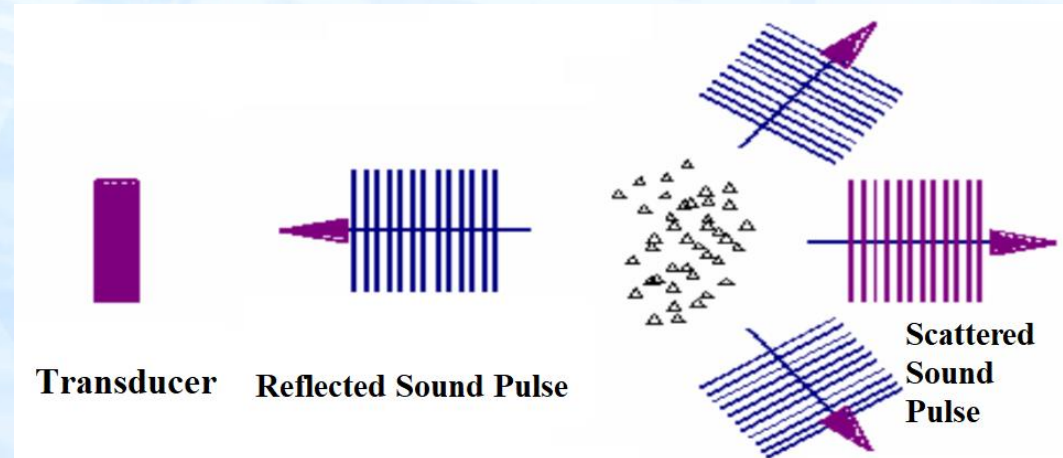
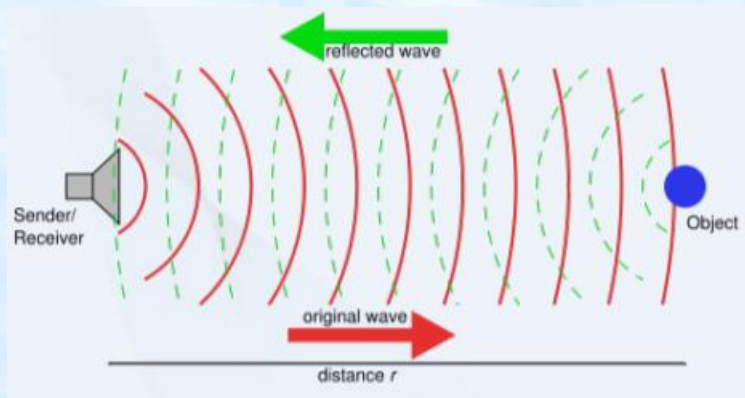
The *Doppler Shift* : $F_d = F_s(V/C)$.



□ The Doppler RADAR

□ Doppler SONAR (like RADAR in air)

SOund NAVigation & Ranging

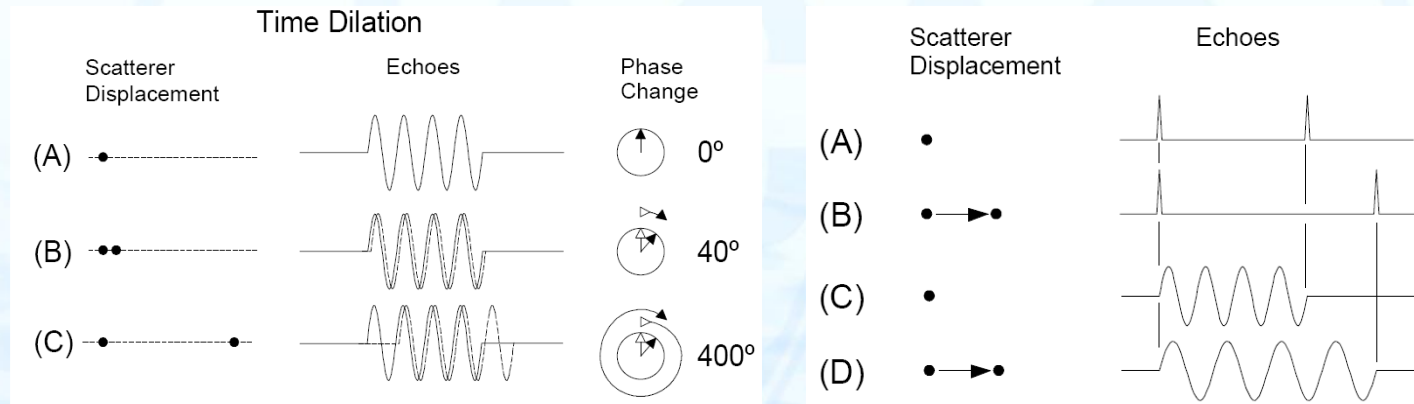


1. Introduction to ADCPs (2/4)



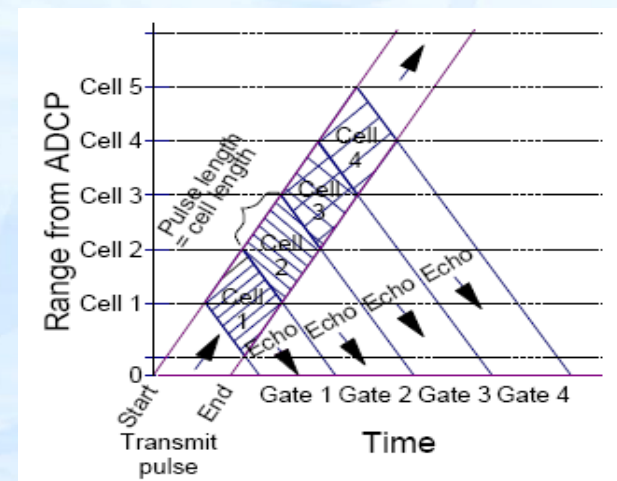
□ BroadBand Doppler Processing

- ❖ Doppler frequency shift and time dilation are equivalent.
- ❖ Autocorrelation techniques



□ Depth Cells and Range Gating

- ❖ Profiles are produced by **range-gating the echo signal**
- ❖ Velocity is averaged over the depth of the **entire depth cell**



1. Introduction to ADCPs (3/4)



Multiple Beams BroadBand Doppler Processing

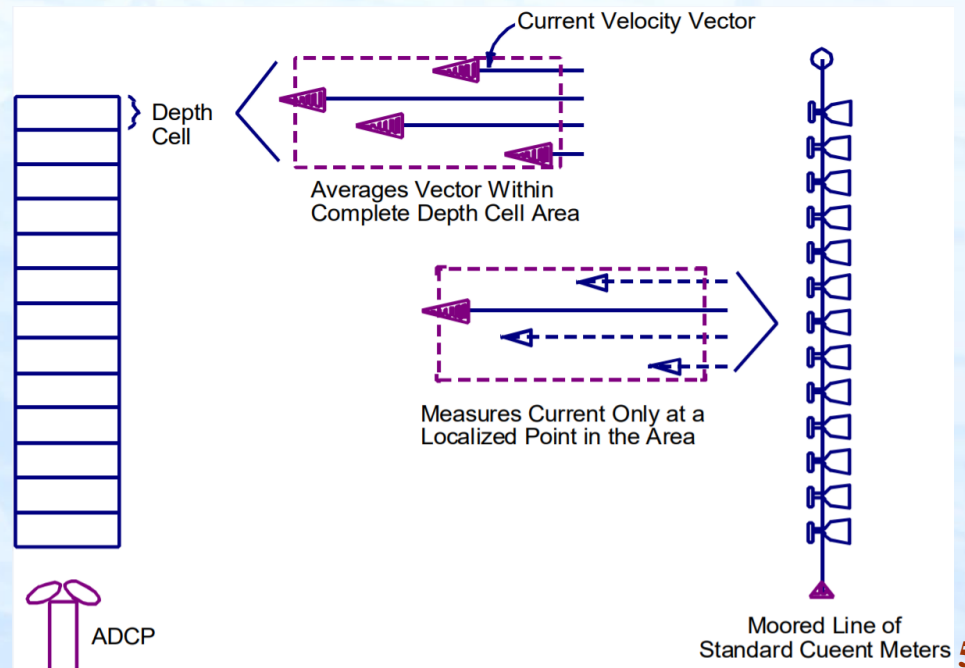
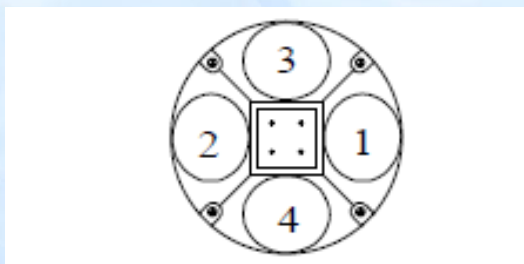
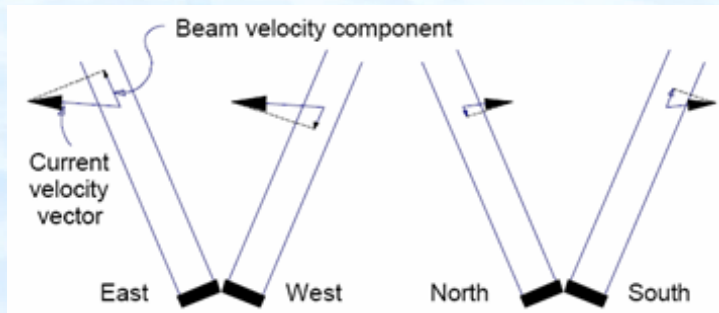
- ❖ from **each pair of beams** get 1 component of horizontal velocity + 1 component vertical velocity
- ❖ **Assumes current Homogeneity** in a Horizontal Layer
- ❖ **Calculation of Velocity** with Four or Five ADCP Beams

$$u_1 = v \sin\theta + w \cos\theta$$

$$u_2 = -v \sin\theta + w \cos\theta$$

$$u_3 = u \sin\theta + w \cos\theta$$

$$u_4 = -u \sin\theta + w \cos\theta$$



1. Introduction to ADCPs (4/4)



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- ❑ **Acoustic Doppler Current Profiler (ADCPs)**
- ❑ are the most universal sensor packages in Ocean and River Observing Systems in the world.



conventional

1. Current profiling
2. Acoustic Ranging

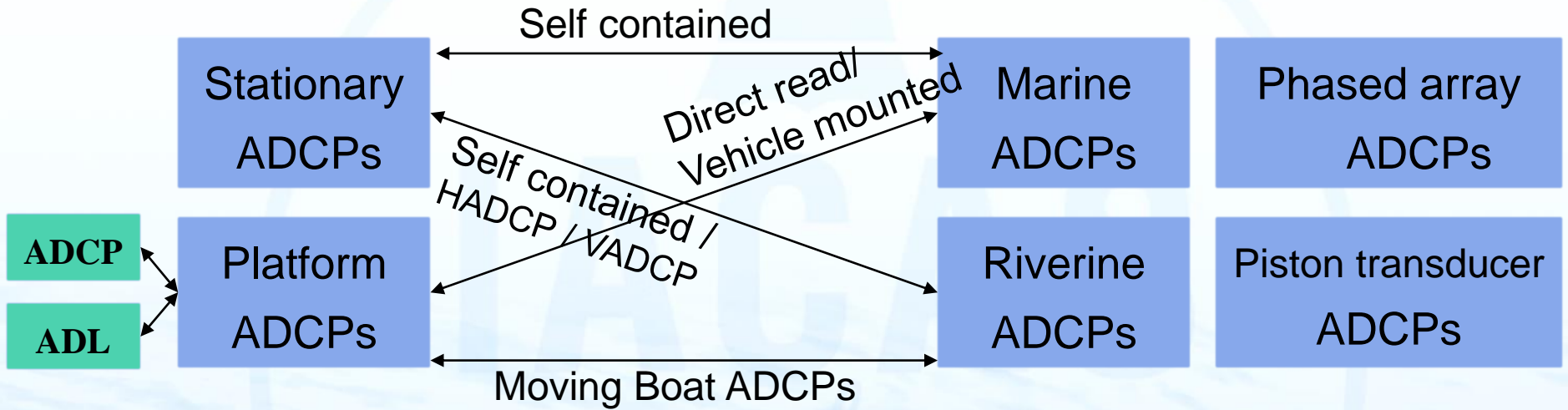
present

1. Water Resource Management - flow in rivers and channels
2. Environmental Monitoring
3. Hydraulic Engineering
4. Scientific Research: sediment transport, environmental
5. Impact studies, modeling

prospective

1. Turbulence
2. Wave
3. Echo profiling - particle or plankton concentration

2. Product Classification (1/5)



US Xylem
Sontek M9



US Teledyne
RDI RiverPro



China HaiYin
RIV-F ADCP



China HaiYin
RIV HADCP

2. Product Classification (2/5)

□ ADCP finishing painting



Transducer acoustic transmission layer



water-tight housing:
engineering plastic or alloy

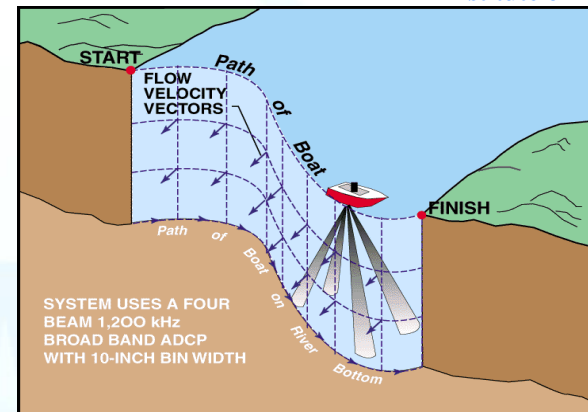


2. Product Classification (3/5)



(1) Moving Boat ADCPs

- ❑ Velocity profiling
- ❑ velocity from bottom tracking / GPS
- ❑ **bottom depth**



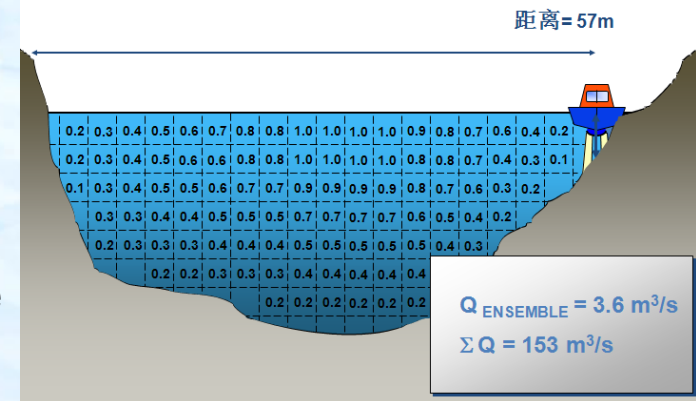
Manned vessel



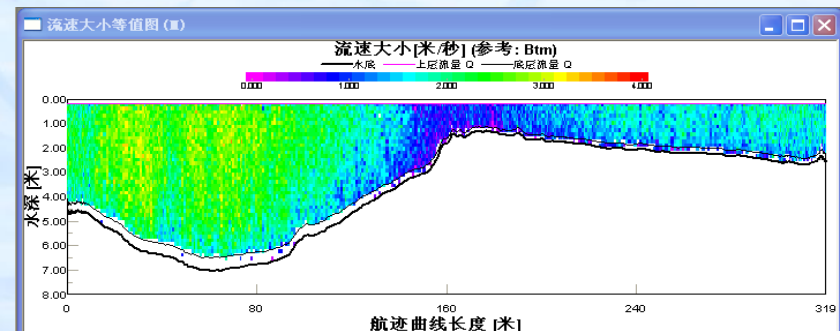
Trimaran



Autonomous Vehicle



- ❑ Flow measurement
- ❑ exquisite profiling information
- ❑ fixed measuring line (Not required)
- ❑ section shape (Not required)



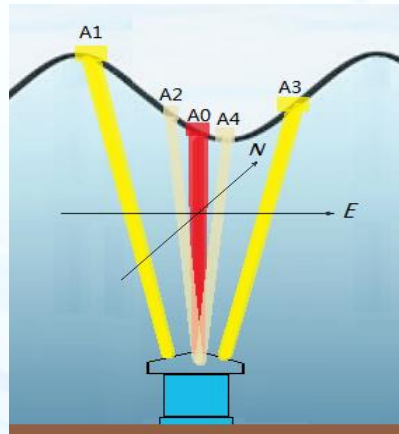
2. Product Classification (4/5)



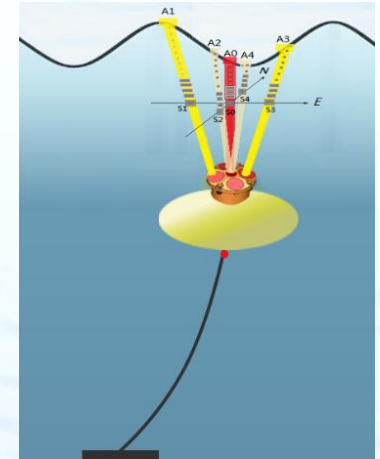
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(2) Platform ADCP / ADL

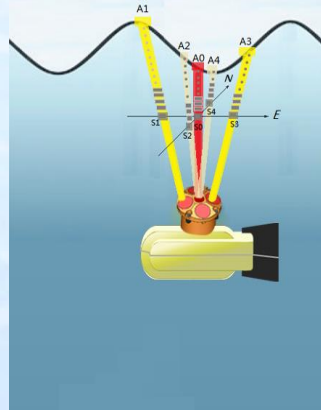
Seabed based platform



Submerged buoy



Vehicle mounted ADCP



Vehicle mounted ADL



2. Product Classification (5/5)



(3) Wave ADCPs

Wave spectrum from ADCP measurements

$$\frac{1}{4} \sum_{i=1}^4 S_{V_i}(\omega, z, d) = T^2(\omega, z, d) S_H(\omega) + S_N(\omega)$$

$$T^2 = \left\{ \omega \frac{\sinh[k(z+d)]}{\sinh(kd)} \cos \beta \right\}^2 + \frac{1}{2} \left\{ \omega \frac{\cosh[k(z+d)]}{\sinh(kd)} \sin \beta \right\}^2$$

Reynolds stresses from ADCP measurements

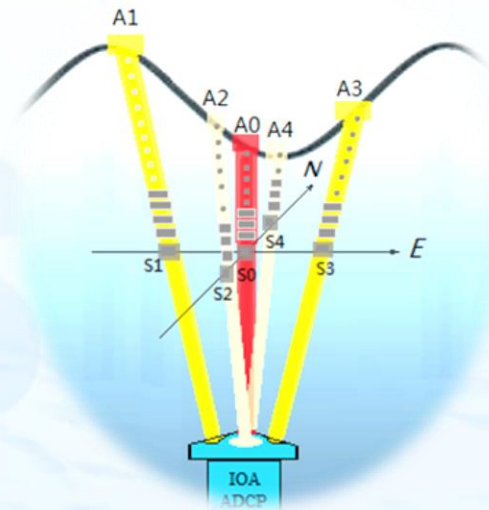
$$u_1 = v \sin \theta + w \cos \theta \quad u_2 = -v \sin \theta + w \cos \theta$$

$$u_3 = u \sin \theta + w \cos \theta \quad u_4 = -u \sin \theta + w \cos \theta$$

$$\overline{u'w'} = \frac{\overline{u_1^2} - \overline{u_3^2}}{4 \sin \theta \cos \theta}$$

$$\overline{v'w'} = \frac{\overline{u_2^2} - \overline{u_4^2}}{4 \sin \theta \cos \theta}$$

Turbulence dissipation from ADCP measurements



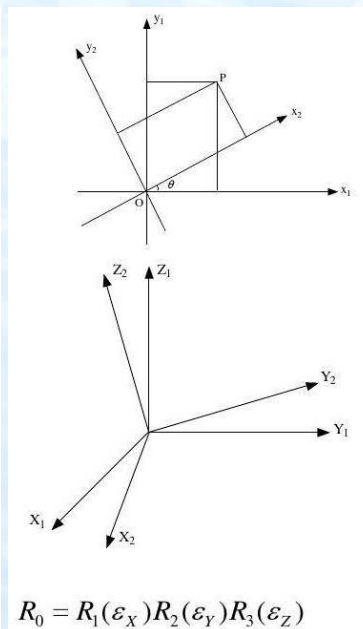
3. Application (QA/QC) (1/6)

- ❑ Velocity (Beam, ADCP, Ship & Earth coordinates)
- ❑ Echo Intensity
- ❑ Correlation Index
- ❑ Percent good (PG)
- ❑ Bottom-track Data (As ADL)

$$R_1(\varepsilon_X) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos \varepsilon_X & \sin \varepsilon_X \\ 0 & -\sin \varepsilon_X & \cos \varepsilon_X \end{bmatrix}$$

$$R_2(\varepsilon_Y) = \begin{bmatrix} \cos \varepsilon_Y & 0 & -\sin \varepsilon_Y \\ 0 & 1 & 0 \\ \sin \varepsilon_Y & 0 & \cos \varepsilon_Y \end{bmatrix}$$

$$R_3(\varepsilon_Z) = \begin{bmatrix} \cos \varepsilon_Z & \sin \varepsilon_Z & 0 \\ -\sin \varepsilon_Z & \cos \varepsilon_Z & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

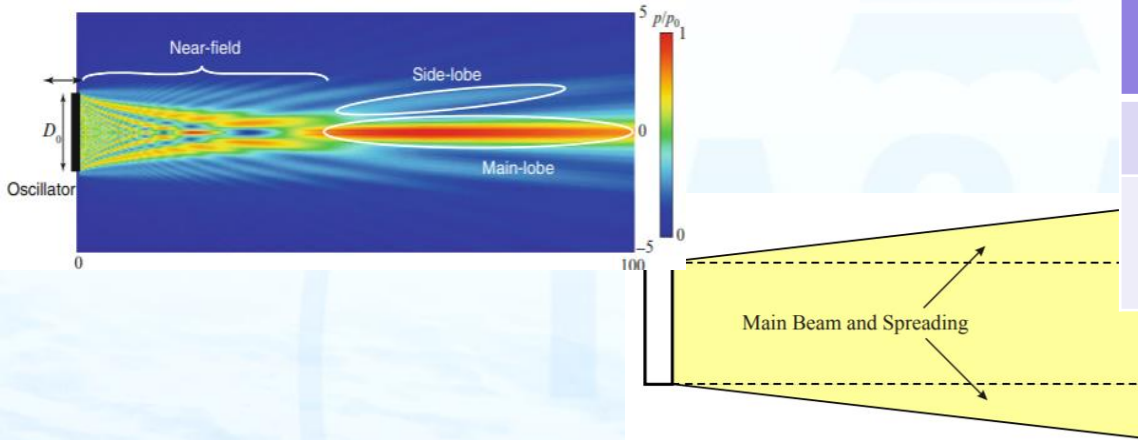


Echo intensity influencing factor

Echo intensity scaled differences between Water body and material interface

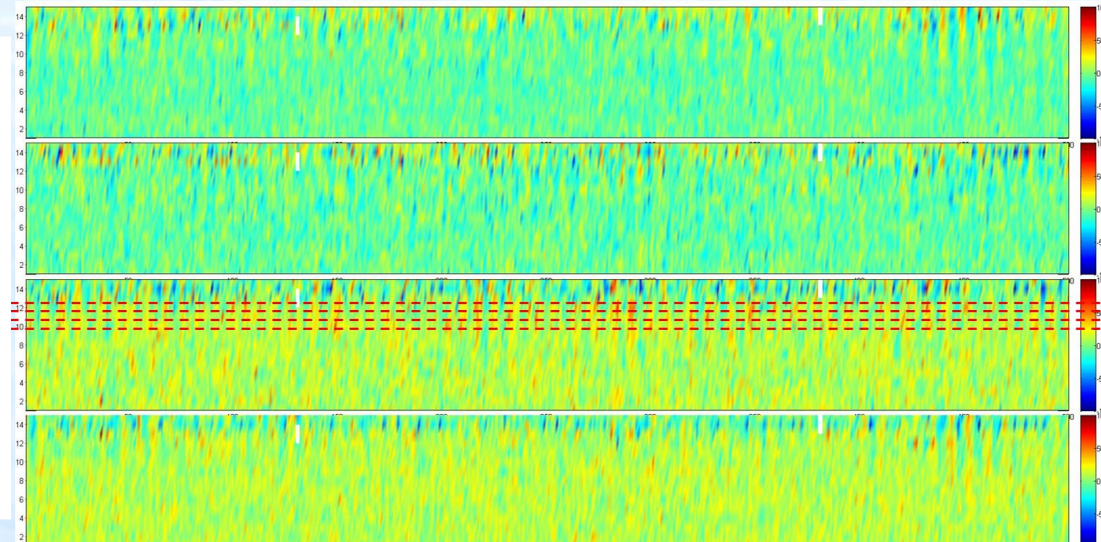
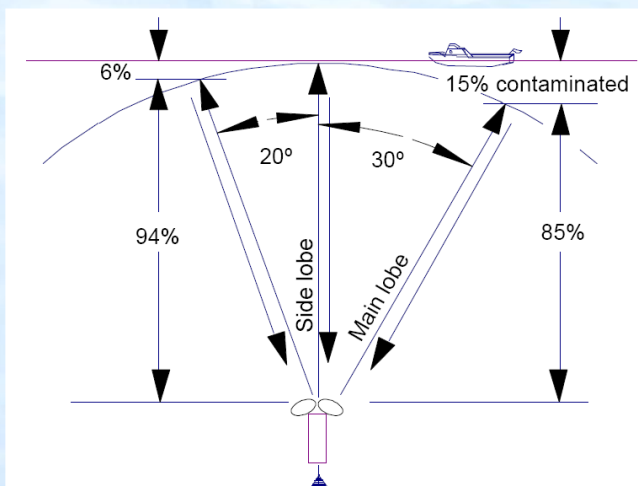
3. Application (QA/QC) (2/6)

Beam Spreading Clearance Zone



	Beam inclination angle	Keep unobstructed
ADCP	20°	10~30
ADL	25 or 30°	5~40 15~45

Near Surface or Bottom Zone

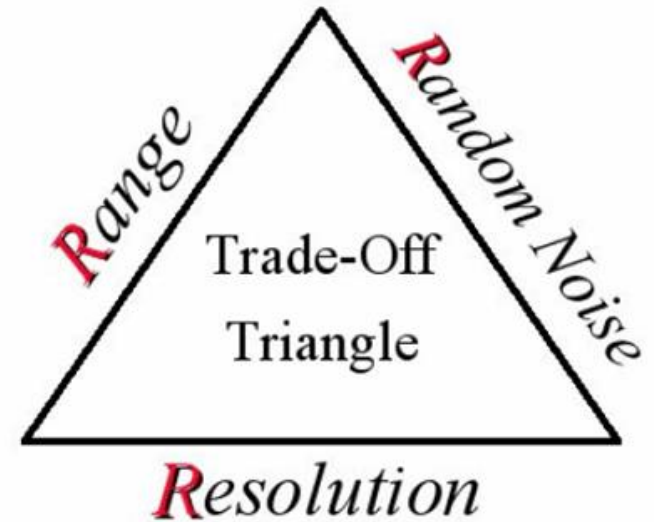


3. Application (QA/QC) (3/6)



□ Setup Parameters

- Depth range of measurements
- Cell size and quantity
- Spacing between measurements:
in depth and time
- Data averaging
- Deployment duration



Trade-off Triangle

□ What's more significant?

According to the battery capacity, we should estimate data quantity and Deployment duration.

As to Direct-Reading / Vehicle-Mounted ADCP or ADL, we should estimate Fastest output rate and transmission speed by serial port or inductive coupling or network transmission.

3. Application (QA/QC) (4/6)

Resolution
Cell Size
Sampling Fs

Range

Random Noise

Frequency

Random Noise vs. Resolution

Random Noise

Velocity precision improves by

Cell Size

Pulse duration

$$\sqrt{\text{No. pings}} \times \text{Depth Cell size}$$

Sampling Rate

Bandwidth Noise

Dynamic Conditions

power consumption

greater heave, pitch and roll of the ADCP
turbulence changes velocity uniformity

data quantity

Scatterer
concentration
&
Absorption
loss

Signal processing noise

power consumption

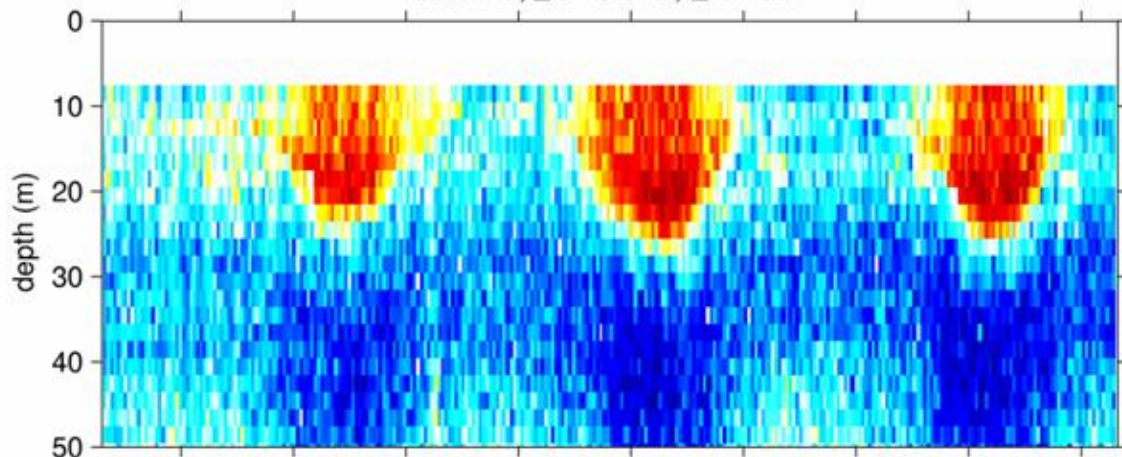
Transmitting pulse coding
Electronics noise

$$\sigma_{ping} = \lambda / (4\pi t_r) \sqrt{(0.5/M) (\rho^{-2} - 1 + \max\{0, 2(1 - M_r/M)\})} \quad (\text{Brumly 1991})$$

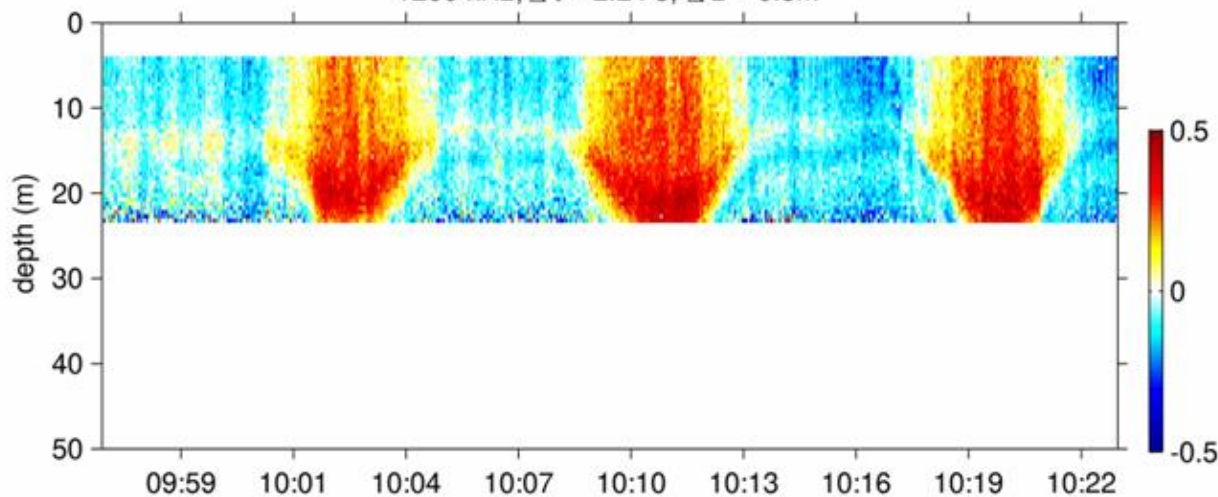
3. Application (QA/QC) (5/6)



300 kHz; $\Delta t = 5.31$ s; $\Delta z = 2$ m



1200 kHz; $\Delta t = 2.24$ s; $\Delta z = 0.5$ m



TRDI workhorse ADCP

Lower frequency

- Bigger Cell Size
- Longer Range
- Lower Sampling Rate

Deep-sea observation

Higher frequency

- Smaller Cell Size
- Shorter Range
- Higher Sampling Rate

shallow sea, nearshore, rivers observation

Wave or turbulence Research

3. Application (QA/QC) (6/6)



❑ ADCP Data QA/QC

- ❑ **preliminary quality control** (Missing data or Echo Intensity abnormal)
- ❑ **correlation test** (Correlation Index)
- ❑ **global test** (element range test)
- ❑ **spike test** (rationality test / Deviation value removal)
- ❑ **Chi-squared Test** (Statistical analysis)
- ❑ **gradient test** (Continuity test/ Jump point removal)
- ❑ **good percentage** (Quality mark/Lag)
- ❑ **manual quality control**

4. About Us - IOA, CAS(1/6)



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Institute of Acoustics, CAS

- ❑ The Institute of Acoustics, CAS (Chinese Academy of Sciences)
- ❑ (1) was established in 1964 as a spinoff of the CAS Institute of Electronics
- ❑ (2) Locations: Beijing, China
- ❑ (3) major R&D unit of ADCP/ADL in China



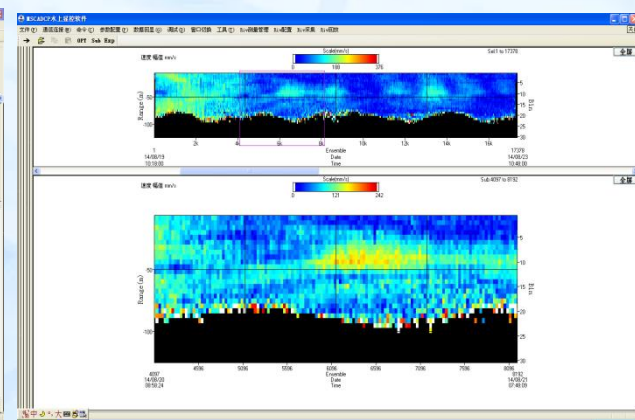
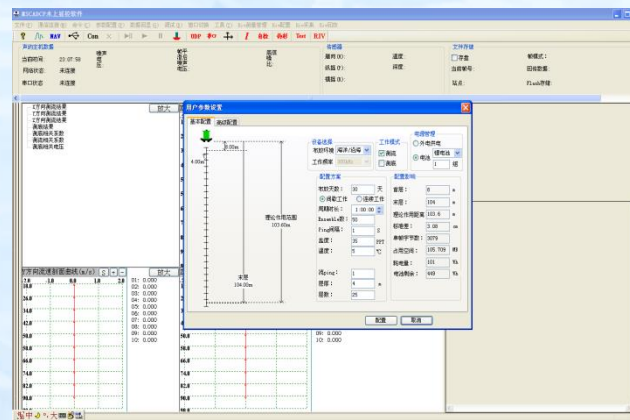
Current measurement
and Velocity Log
Research Group

4. About Us -- Marine ADCP(2/6)



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- Series of self contained and direct reading ADCP for long-term fixed-point flow measurement
- supporting software
- Inspection testing equipment for ADCP fast factory test on land
- Effectively pool tested and offshore tested



4. About Us -- Marine ADCP(3/6)



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- applied in China's territorial waters, the global oceans and the antarctic and Arctic Poles.
- Self-sustaining application obtained data for **2 years Maximum**.
- **deep-sea ADL** has been used in 6000m AUV, Jiaolong manned submersible, 6000m ROV and acoustic deep tow, etc.

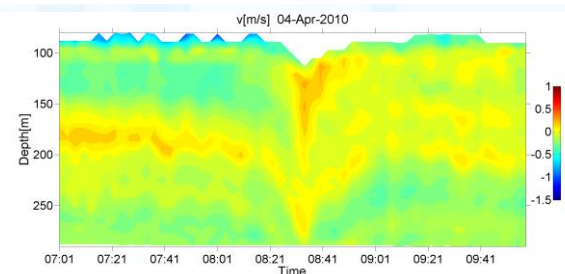
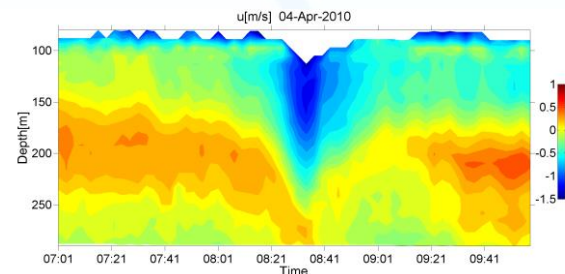
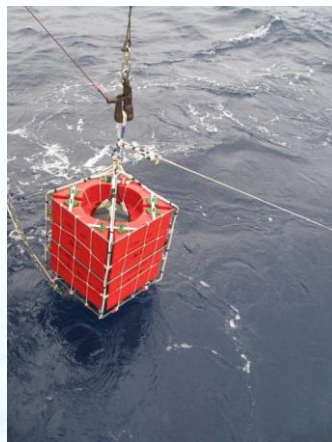
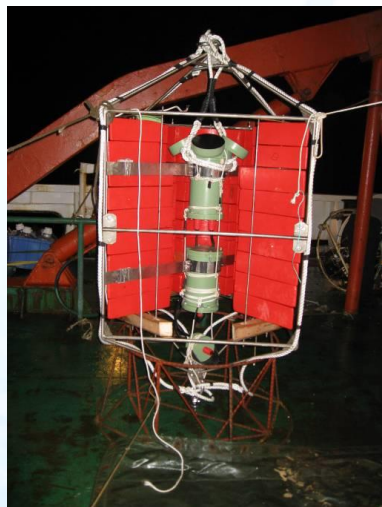


4. About Us -- Marine ADCP(4/6)



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Reliability verification test on submarine buoy



Long-term deployment of self contained ADCP on submersible buoys An example of internal solitary wave

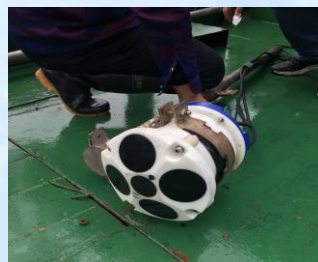
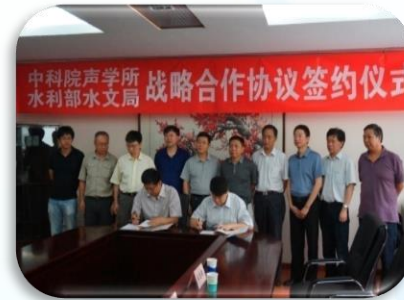
- over 5 months, 1000 m depth, ADCP at 250 m below sea surface
- observed several internal wave processes
- ADCP transducers, structure and hardware have verified at actual deep-sea environment

4. About Us - Riverine ADCP(5/6)



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- ❑ **IOA-CAS signed cooperation agreements** with the Hydrological Bureau of the Ministry of Water Resources, the Hydrological Bureau of the Yangtze River Commission and the Hydrological Bureau of the Yellow River Commission to promote the R&D of Riverine ADCP
- ❑ **RIV-600 ADCP** as new product appraisal of the Ministry of Water Resources
- ❑ River or stream flow measurement technology and **real-time observation system**
- ❑ Supporting software IOARiver
- ❑ **RIV-1200 ADCP** suitable for shallow river or stream
- ❑ **H-ADCP and 5-Beams ADCP**



4. About Us - Riverine ADCP(6/6)



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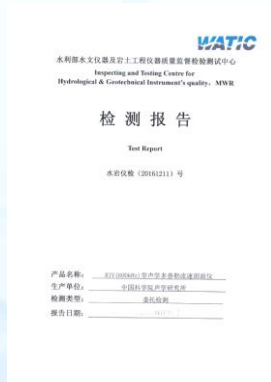
Comprehensive performance test of Riverine ADCP



2013年9月小浪底水文站试验



2015年4月长江南京站试验



水利部水文仪器及岩土工程仪器质量监督检测中心	
产品检测测试报告	
产品名称	声学多普勒流速剖面仪 型号规格 K17 (2000Hz)
生产单位	中国科学院声学研究所 联系电话 810 8537060-204
抽样地点	样品种类 1只
样品编号	委托单位 中国科学院声学研究所
委托单位	委托单位 810 8537060-204
地址	地址 北京市海淀区中关村东路33号
检测/送样人	检测/送样日期 2016.10.20
送样方式	检测日期 2016.10.20~2016.10.31
检测地点	检测环境 室内检测, 标准温度
检测项目	检测项目 声学多普勒流速剖面仪性能测试
检测依据	检测依据 水利部行业标准 SL27-2004 《声学多普勒流速剖面仪》, SL7-2000 《水文仪器及岩土工程仪器质量监督检测中心》, SL27-2004 《声学多普勒流速剖面仪》, SL7-2000 《水文仪器及岩土工程仪器质量监督检测中心》
检测结果	检测结果 合格, 符合水利部行业标准 SL27-2004 《声学多普勒流速剖面仪》, SL7-2000 《水文仪器及岩土工程仪器质量监督检测中心》
备注	备注



2015年4月
上海松浦大桥站试验



2015年5月
江西峡江站试验



2015年6月
广东马口站试验



4、Contact Us



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Institute of Acoustics, CAS



Institute of Acoustics, Chinese Academy of Sciences
Doppler Research Group @ Laboratory of Marine Acoustics Technology

Rao Liang raoliang@mail.ioa.ac.cn (reporter)

Deng Kai dengk@mail.ioa.ac.cn (Indirector)

- ❑ **Marine and Riverine ADCP have been used in oceanographic scientific research and river hydrological operational observation**
- ❑ **High cost performance Rate**
- ❑ **Advanced technology & Convenient technical support, greatly improves the use efficiency of ADCP**
- ❑ **University-industry Cooperation,** improves the research level and systematizes hydrological monitoring





IACAS

谢谢

Thank You