







UNESCO/IOC – NOAA ITIC Training Program in Hawaii (ITP-TEWS Chile)

TSUNAMI EARLY WARNING SYSTEMS

AND THE PACIFIC TSUNAMI WARNING CENTER (PTWC) ENHANCED PRODUCTS

TSUNAMI EVACUATION PLANNING AND UNESCO IOC TSUNAMI READY PROGRAMME

19-30 August 2024. Valoaraiso. Chile

TWC Operations: Travel Time and Amplitude Forecasting – Methods, Limitations, Uncertainty, Sensitivity Studies (Location, Depth, Magnitude)

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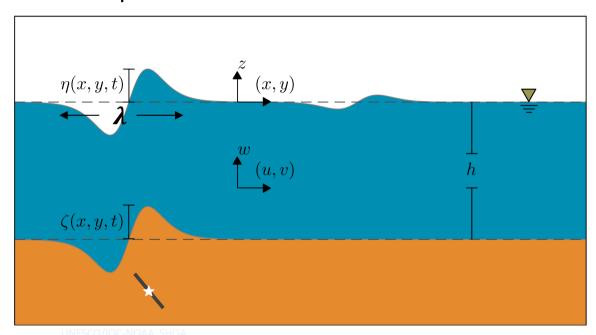
Outline

Quick Review of Essentials

The Travel Time Problem

Amplitude Forecasting

Tsunamis are primarily "long waves". The term "long" refers to the fact that, in open waters, **tsunami waves** have lengths several times larger than water depth.

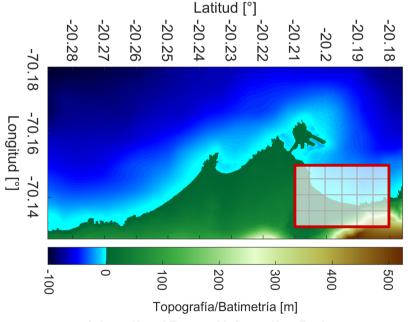


Long wave approximation

 $\lambda \gg h$

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These waves travel depending on the water depth. The surface that defines these depths is called **Bathymetry** and is one of the main inputs for tsunami modeling.



Each cell is linked to a geographical coordinate and a depth/height.

1,2	-6	-5,5	-4	-4,1	-6
2,3	.0,2	-1,2	-2,0	-2,4	-3,1
3,2	3,8	2,4	0,2	0,5	1,1
4,5	6,8	4,1	5,5	9,4	15

The sign change defines the shoreline

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So, tsunami waves travel on a bathymetry... at what velocity? It depends on the wave frequency.

As any wave, tsunamis can be decomposed in different frequencies (Fourier Transform)

In the long wave predominance, $kh \ll 1$, $C_{ph} = C_g = \sqrt{gh}$

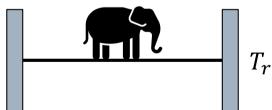
For h = 4 and h = 5 km, the speed is around **713 and 800 km/h**

In fact, the situation is somewhat more complicated.

Other effects may induce change in the wave travel. Let's see one example

Crossing a perfectly rigid bridge

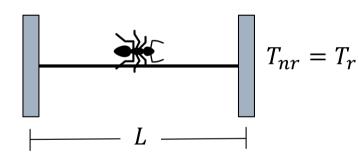
$T_r = \frac{L}{v_o}$



$$T_r = \frac{L}{v_e}$$

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Crossing an elastic bridge

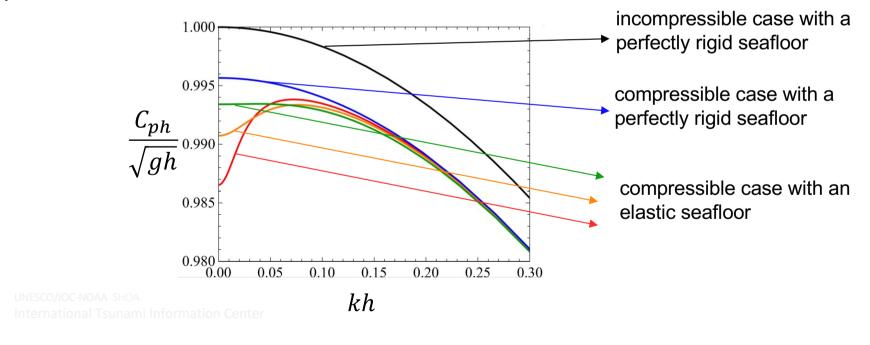




$$T_{nr} = \frac{L + \Delta L}{v_e} = T_r + \Delta T$$

In fact, the situation is somewhat more complicated.

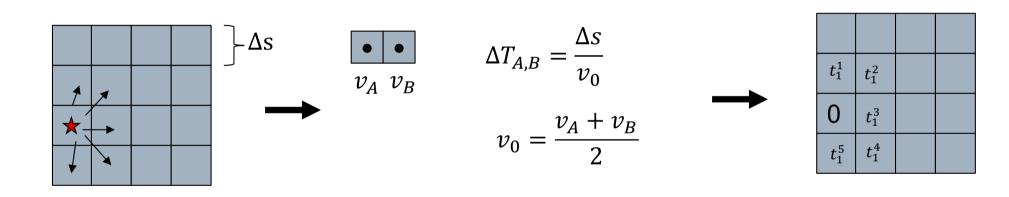
Other effects may induce change in the wave travel. Let's see one example In a similar way, different wavelengths respond differently to the elastic properties of the seafloor.



The Travel Time Problem

The Travel Time Problem

- Source Observer Problem
- Common Methods
 - □ The TTT (*Tsunami Travel Time*): Huygen's Principle
 - Ray Tracing
 - □ Direct Tsunami Propagation Solvers



We compute the three posible time increments. We take the minimum!

$$\Delta T_{A,B} = \frac{\Delta s}{v_0}$$

t_1^1	t_{1}^{2}	
0	t_{1}^{3}	
t_{1}^{5}	t_1^4	



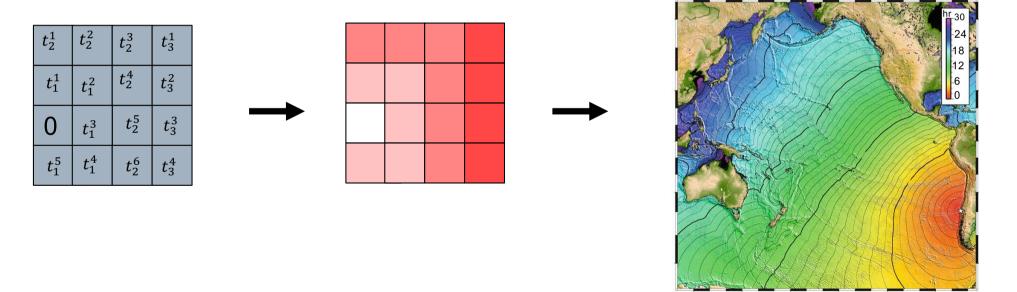
t_2^1	t_2^2	t_2^3	
t_1^1	t_1^2	t_2^4	
0	$t_1^3 -$	t_2^5	
t_{1}^{5}	t_1^4	t_2^6	

Let's say that t_1^3 produces the minimum time increment, then

$$t_2^5 = t_1^3 + \Delta T_{A,B}$$

Conect points with the same time (isochrones)

Apply it to real bathymetry



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- Sensitive to bathymetry data
- Requires high computer power
- Needs high optimization to reduce computation times
- Do not consider wave frequencies nor second order effects
- Has relatively high uncertainty for far field arrival times

Ray Tracing

Eikonal Equations for Tsunami rays

 θ : colatitude

 ϕ : longitude

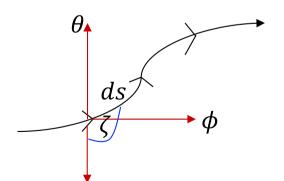
R: Earth Radius (6371 km)

C: Phase Velocity

$$\frac{\mathrm{d}\theta}{\mathrm{d}s} = \frac{1}{R}\cos(\zeta)$$

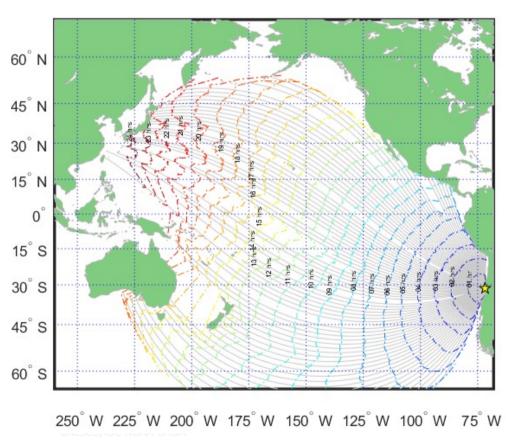
$$\frac{\mathrm{d}\phi}{\mathrm{d}s} = \frac{1}{R} \frac{\sin(\zeta)}{\sin(\theta)}$$

$$\frac{\mathrm{d}\zeta}{\mathrm{d}s} = \frac{\sin(\zeta)}{R} \frac{1}{C} \frac{\partial C}{\partial \theta} - \frac{\cos(\zeta)}{R \sin(\theta)} \frac{1}{C} \frac{\partial C}{\partial \phi} - \frac{\sin(\zeta)\cot(\theta)}{R}$$



$$ds = C \times dt$$

Ray Tracing



Again, connect ray points at equal times: this will produce Isochrones of the wavefront

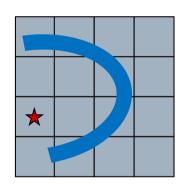
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Ray Tracing

- Sensitive to bathymetry data
- Requires high computer power
- It could need an excessive number of rays to cover the whole bathymetry, making the process slow.
- Has relatively high uncertainty for far field arrival times

Tsunami Propagation

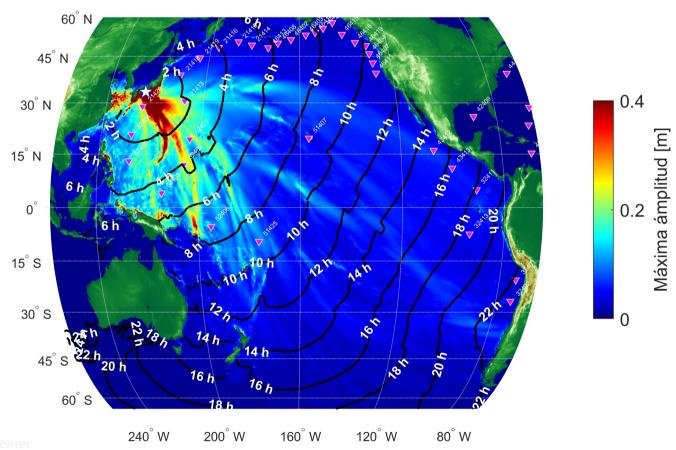
There are plenty of Tsunami Solvers out there, most of them are based on a version of the Non-Linear Shallow Water Equations (NLSWE), treated in finite difference schemes.



Arrival time is defined at every point amplitude exceeds a preset threshold (let's say 1 cm).

Tsunami Propagation

Hypothetical source in the Nankai Trough



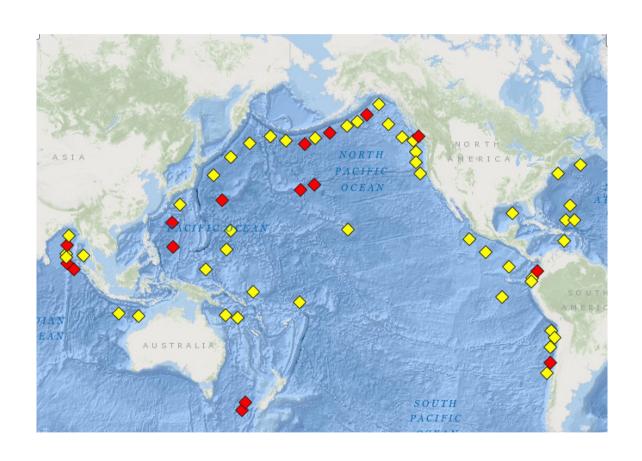
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Tsunami Propagation

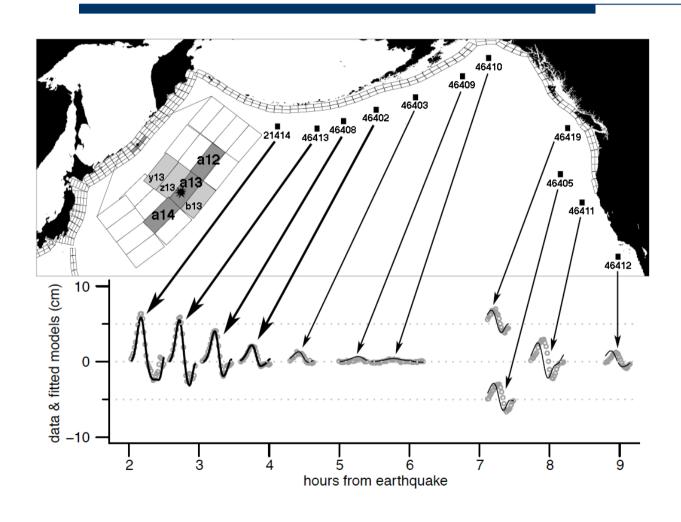
- Sensitive to bathymetry data
- Requires high computer power
- Sensitive to the source determination
- May vary from different numerical models

Tsunamis are recorded by **Tsunamimeters.**

In open waters, the waves have essentially linear behavior, and those records can be employed for an **inversion process**.

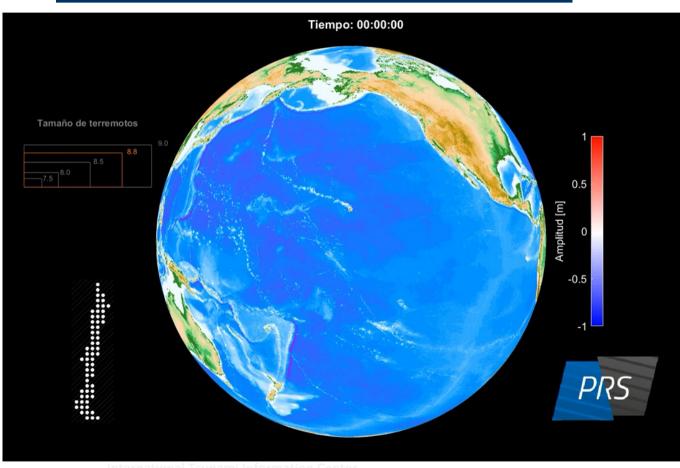


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Predefined source candidates are set and then, selected and weighted according the data retrieved from the DART buoys.

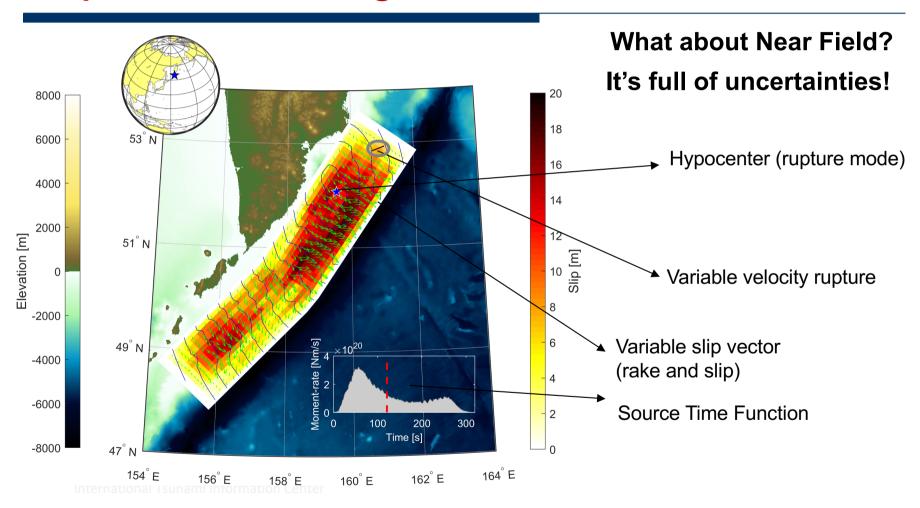
Once the possible source is reconstructed, a forward model is run.

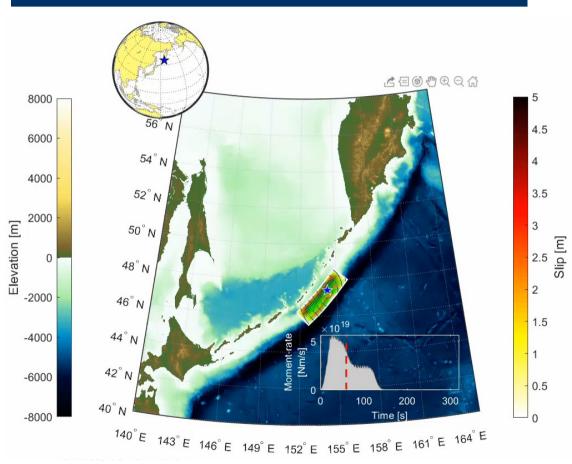


Evidently, this only has sense for communities where the waves have not yet arrived after the whole has finished.

Far Field!

- Sensitive to bathymetry data
- Sensitive to data acquiring
- Not useful for tsunami early warning in the Near Field case
- Specific Tsunami Inundation Models depend on data that may not exist, and highly computational expensive.





There are infinitely many valid sources and it's not possible to perform (yet) to a reliable inversion and predict amplitudes before the tsunami impact.

Then, how we tackle the Early Warning Problem in the Near Field?

Soon, in a talk, this Will be discussed;)

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Thank You

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